

# Computing moment polytopes and applications

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Work with:

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First : what are moment  
polytopes ?

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$$\subseteq \mathbb{R}^a \times \mathbb{R}^b \times \mathbb{R}^c$$

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$$\frac{\overline{T_1}^* T_1}{\text{Tr}(\overline{T_1}^* T_1)}$$

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$$\Delta^{\text{geom}}(T) := \left\{ (\text{spec } \mu_1(T'), \text{spec } \mu_2(T'), \text{spec } \mu_3(T')) \mid T' \in \overline{G \cdot T} \right\}$$

$$\subseteq \mathbb{R}^a \times \mathbb{R}^b \times \mathbb{R}^c$$

Theorem [Mumford - Ness]

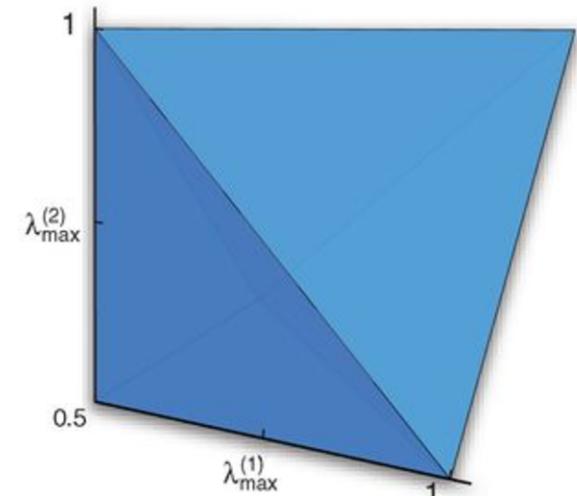
$$\Delta^{\text{repr}}(\tau) = \Delta^{\text{geom}}(\tau)$$

and it is a rational (convex compact) polytope

We denote it with  $\Delta(\tau)$ .

## Examples

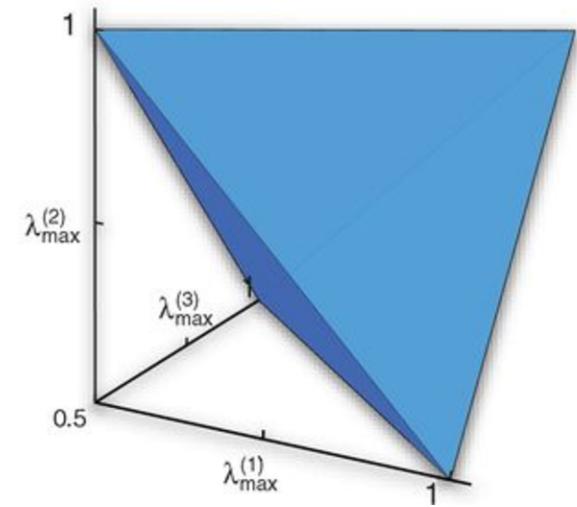
$$\Delta \left( \sum_{i=1}^2 e_i \otimes e_i \otimes e_i \right) = \text{conv} \left\{ \begin{array}{c} \overbrace{\mathbb{R}}^2 \quad \overbrace{\mathbb{R}}^2 \quad \overbrace{\mathbb{R}}^2 \\ (1, 0, \quad 1, 0, \quad 1, 0) \\ (\frac{1}{2}, \frac{1}{2}, \quad \frac{1}{2}, \frac{1}{2}, \quad \frac{1}{2}, \frac{1}{2}) \\ (1, 0, \quad \frac{1}{2}, \frac{1}{2}, \quad \frac{1}{2}, \frac{1}{2}) \\ (\frac{1}{2}, \frac{1}{2}, \quad 1, 0, \quad \frac{1}{2}, \frac{1}{2}) \\ (\frac{1}{2}, \frac{1}{2}, \quad \frac{1}{2}, \frac{1}{2}, \quad 1, 0) \end{array} \right\}$$



$$\Delta \begin{pmatrix} e_1 \otimes e_1 \otimes e_2 \\ + e_1 \otimes e_2 \otimes e_1 \\ + e_2 \otimes e_1 \otimes e_1 \end{pmatrix} = \text{conv} \left\{ \begin{array}{c} (1, 0, \quad 1, 0, \quad 1, 0) \\ (1, 0, \quad \frac{1}{2}, \frac{1}{2}, \quad \frac{1}{2}, \frac{1}{2}) \\ (\frac{1}{2}, \frac{1}{2}, \quad 1, 0, \quad \frac{1}{2}, \frac{1}{2}) \\ (\frac{1}{2}, \frac{1}{2}, \quad \frac{1}{2}, \frac{1}{2}, \quad 1, 0) \end{array} \right\}$$

↳ *W, slices:*

$$\begin{matrix} 0 & 1 & 1 & 0 \\ 1 & 0 & 0 & 0 \end{matrix}$$



# Why care?

- Fundamental objects in quantum information

[Walter, Doran, Gross, Christandl — Entanglement polytopes:  
Multipartite information from Single-Particle Information, 2013]

- Applications in matrix multiplication complexity: quantum functionals

[Bürgisser, Ikenmeyer — Geometric complexity theory and tensor rank, 2011]

[Christandl, Urana, Zuiddam — Universal points in the asymptotic spectrum of tensors, 2018]

- Examples of general moment polytopes, central objects in scaling problems

[Bürgisser, Franks, Garg, Oliveira, Walter, Wigderson — Towards a theory of non-commutative optimisation (...), 2019]

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Computing Entanglement polytopes

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$$\text{supp}(T) := \{(e_i, e_j, e_k) \mid T_{i,j,k} \neq 0\}$$

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Example:

$$\text{supp}(W) = \text{supp} \begin{pmatrix} e_1 \otimes e_1 \otimes e_2 \\ + e_2 \otimes e_2 \otimes e_1 \\ + e_2 \otimes e_1 \otimes e_1 \end{pmatrix} = \left\{ \begin{array}{l} (1, 0, 1, 0, 0, 1), \\ (1, 0, 0, 1, 1, 0), \\ (0, 1, 1, 0, 1, 0) \end{array} \right\}$$

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where  $T' \in GL \cdot T$  is generic

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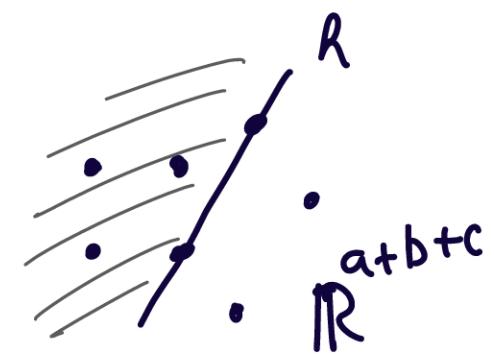
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## Inequalities

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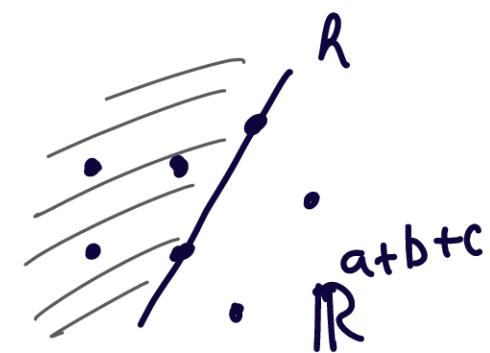
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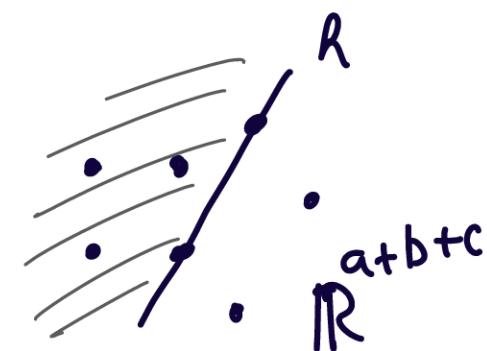
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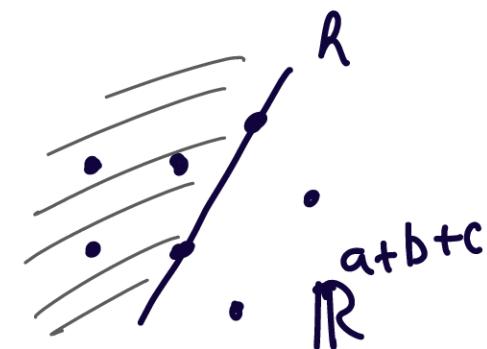
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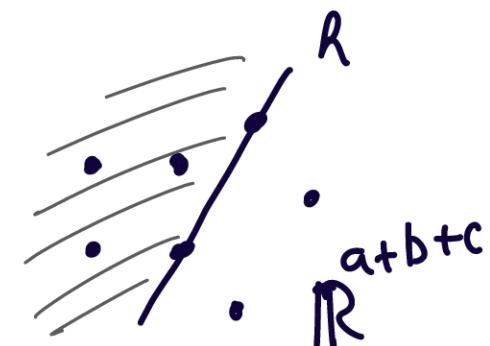
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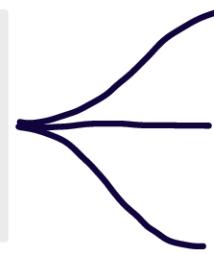
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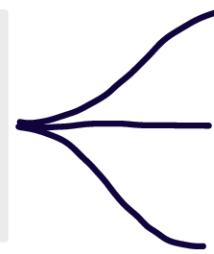
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e.g. using  
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Tensor	Inequalities					Vertices	Runtimes	
	All	Not generic	Maxranks	Attainable	Final		$\mathbb{Q}$	$\mathbb{F}_q$
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still going  
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